

ZOOMLION ZCT1200V643

TELESCOPIC BOOM CRAWLER CRANE

TECHNICAL SPECIFICATIONS

GQ06600702700000EN

Zoomlion Heavy Industry Science and Technology Co. Ltd

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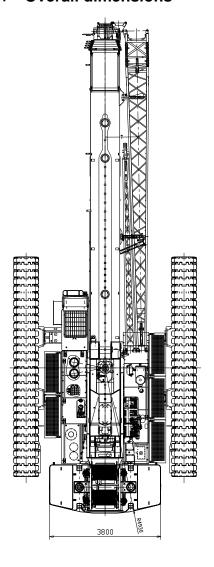
TECHNICAL SPECIFICATIONS

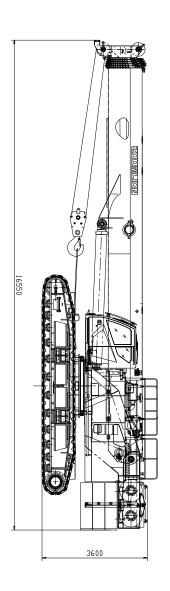
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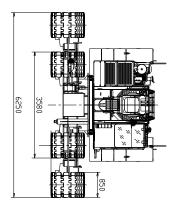
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1. Overall dimensions and main technical parameters

1.1. Overall dimensions







1. 2. Main technical parameters

Table – Main technical parameters

Max. lifting				Remarks
	Max. lifting capacity		120	
Max. lifting moment		t×m	450	
Main boon	n length	m	13.85-65.7	
Jib length		m	10.4-17.5	Optional
Max. lengt	h of main boom with	m	65.7+17.5	
Main boon	n angle	0	-1.5-80	
Jib angle		0	0, 15, 30	
Max. single main hoist	e rope speed of the ing winch	m/min	140	Unloaded, the 4th drum layer
J	e rope speed of the oisting winch.	m/min	135	Unloaded, the 3th drum layer
Boom derr	icking up time	s	80	
Slewing speed		rpm	0-1.6	
Traveling	Traveling speed		0-1.5	
Max. grade	eability	%	40	
Ground pr	essure	МРа	0.1	
Deadweigl	nt	t	106	With the main hook installed (excluding jib)
Counterwe	eight	t	34	
Overall dir	nensions (L × W × H)	mm	16550×6250(3580)×3600	
	Model		Weichai WP7G300E473	
	Rated power / rotational speed	kW/rpm	220.7/2200	
Engine	Max. output torque / rotational speed	Nm/rpm	1200/(1400-1600)	
Exhaust emission		/	Chinese National Stage IV	
Distance between track center × crawler contact length × crawler width		mm	2730×5970×850	Crawler carrier retracted
		mm	5400×5970×850	Crawler carrier extended
Noise	Noise level outside	dB	≤107	

	e operator's cab ring operation			
No	oise level in the			
оре	erator's cab during	dB	≤85	
ope	eration			

Note:

- 1. The single rope speed of the winch, slewing speed and traveling speed vary with the load.
- 2. The ground pressure is an average value, and the actual maximum ground pressure should be determined according to actual lifting conditions.

1. 3. Main technical features

Strong lifting capacity

The boom consists of 6 oval-shaped boom sections which can extend to a maximum length of 65.7 m, contributing to the crane's superior comprehensive lifting capacity and securing Zoomlion's leadership in the industry. The independently designed plate-type boom head and compact boom end realize optimal overlapping ratio as well as stronger lifting capacity of the main boom. The second generation of free boom telescoping technology, which is novel in the industry, increases stability during telescoping and brings the overall vehicle with higher anti-tipping capacity.

High work efficiency

An electric proportional control joystick is installed in the crane, which is capable of compounding movements of the main and auxiliary winches, the derricking mechanism, the slewing mechanism and the telescoping mechanism, therefore greatly increasing the crane's lifting efficiency.

The crane is characterized in its convenient, flexible, stable and reliable operations which can be adjusted in a stepless way.

Single rope speed of the hoisting winch 1 and 2 can reach 140 m/min (at 4th layer on the drum).

Stronger single wire rope pulling force

The main and auxiliary winches use a standard ϕ 22 anti-twisting wire rope, whose single rope pulling force can reach 9 t.

Optimization of transportation, assembly and dismantling

Easy for transfer between working sites; the whole vehicle can be transported in one truck after its counterweight is removed.

The movable counterweight plates can be installed and removed conveniently by a counterweight handle. Therefore they are also convenient for transportation.

The crawler carriers can be extended and retracted, and the maximum transport width of the crane is 3.58 m.

Vertical outriggers are installed to provide convenience during crawler carrier dismantling

process.

1.4. Main boom and telescoping mechanism

The box-shaped main boom consists of 6 boom sections made of low-alloy high-strength steel plate, providing the boom with excellent bending-resistance capacity, superior load

bearing capacity, light deadweight, large lateral stiffness and low end deflection.

The new plate-type boom head and compact boom end realize optimal overlapping ratio of

adjacent boom sections. The boom head adopts an independently designed imbedded sliding block structure and a series of optimized designs, having the deadweight of the boom greatly

decreased and the stress on the boom evenly distributed to avoid partial distortion.

Furthermore, the boom has good guidance quality and adjustability.

A single cylinder pinning mechanism is installed to control boom telescoping movements. It is

automatically controlled by a program to realize mechanical interlocking and telescoping in

sequence.

1.5. Jib

The jib is consisted of two jib sections of variable cross-section structure, realizing superior

force bearing performance. It is secured onto the first one through pins.

There are two jib lengths, i.e. 10.4 m and 17.5 m. The jib section I is hinged to the head of the

top boom section through pins. The jib can be installed at one of the three angles onto the boom, i.e. 0°, 15° and 30°. Change of jib angles is realized conveniently through a rotary shaft

and sliding groove.

1. 6. Hoisting mechanism

It consists of a main hoist mechanism and an auxiliary hoist mechanism.

The two hoist mechanisms are driven by an axial plunger hydraulic motor with a built-in

planetary gear reducer to lift or lower the hook.

A brake is fitted between the motor and reducer.

The two winch mechanisms can be controlled independently and also can carry out

simultaneous movements.

The auxiliary hoist winch is of same model of the main winch, and both of them adopt a

variable motor. The main winch is installed with an overlowering protection device which gives

alarm when there are only 3 wraps of wire rope left on the drum.

The sealed-in planetary reducer is of a compact structure, light deadweight and high

reliability.

Specifications for high-tensile torsion resistant hoist rope:

Diameter: φ22.0 mm

Strength grade: 1960 N/mm²

5 / 24

Length of main hoist rope: 320 m

Length of auxiliary hoist rope: 175 m

Single rope pulling force: 9 t

1. 7. Derricking mechanism

A front-mounted derricking mechanism, single oil cylinder, enables the boom to derrick within -1.5°-80°. A balance valve is installed in the cylinder to ensure stable derricking operations.

1.8. Slewing mechanism

The slewing mechanism consists of a hydraulic motor and planetary reducer. The dual-reducer slewing mechanism, and the slewing ring which is external engaged with the reducer, realizes large output torque and stable transmission of force.

The crane is capable of conducting controllable free swing during lifting operation where the crane is automatically aligned to the slewing center relative to the load.

A slewing cushion valve and a normally-closed brake are installed to ensure stable and reliable slewing.

1.9. Engine

Engine model: Weichai WP7G300E473

Type: six-cylinder in-line, intercooling turbo-charged diesel engine

Rated power: 220.7kW/2200r/min

Max. torque: 1200N.m/1400-1600r/min

Emission standard: Chinese National Stage IV

Fuel tank capacity: 600L

1. 10. Hydraulic system

The superstructure adopts an electro-hydraulic pilot proportionally controlled hydraulic system which is controlled by the integrated computer, therefore high operational comfort, sound fine and simultaneous movements are realized. The hydraulic system is a variable system combines open-type and close-type characteristics. Small hydraulic loss, high working efficiency and movement accuracy, stable and reliable operations and stepless speed adjustment are assured. A counterweight handling system and a cab tilting mechanism are also installed. Stable startup and braking performance and high system reliability are assured.

The oil cooler for hydraulic system: a radiator driven by a high-power hydraulic motor, 47 kW

Hydraulic oil tank capacity: 1000 L

1.11. Electrical system

24 Volt DC, negative ground, two batteries of 200AH each.

The electrical system of the crane includes the power supply, engine start, engine shutdown, indicator lights, warning devices, illumination devices, fan, wiper, horn, hoisting limiter, hydraulic oil cooling fan, concentrated display panel, load moment limiter, safety devices etc. which not only ensure safe operation of the crane but also provide a good working environment.

Modular design, CAN bus control technology and gateway design are adopted for the electrical system, realizing clear and simple system architecture and convenience and easy maintenance. Each control unit can not only work independently to control its executive mechanism, but also communicate in real-time through the CAN bus network with gateways, therefore ensuring accurate, synchronous, safe and reliable electric control. Conventional switches, joystick and indicator light boards are replaced by integrated control pane, joysticks and indicator light panels controlled by CAN bus, which greatly reduces number of wiring and connectors and enhances system reliability. The conventional low gear switch is replaced by a stepless rotary switch, which improves fine movements and realizes more convenient and accurate operations.

The load moment limiter and 10.4-inch large monitor screen can effectively monitor all parameters related to working status, and analyze them to provide necessary pre-alarms, alarms or actively cut off dangerous movement to ensure working safety.

1.12. Counterweight

A hanging counterweight system installed with movable counterweight plates, whose total weight is 34 t.

The movable counterweight plates are installed and removed through the counterweight handler installed at the tail of the slewing platform. They are stacked up and convenient for transportation.

There are two fixed balancing counterweight plates, whose total weight is 11 t.

1. 13. Operator's cab

The spacious and full-closed cab is equipped with a safety windshield glass, an adjustable seat with armrest and headrest, an intermittent wiper and a window water injector, and covered with soft interior materials. It can be tiled upward or downward.

Control boxes

The control boxes on both side of the cab are installed with various electrical switches and an emergency stop button, etc. They can be adjusted with the operator's seat.

Joysticks and travel gear pedals

The hydraulic control system consists of two joysticks located in left and right side of the operator's seat and three travel gear pedals. These joysticks and pedals control movements of main valves through pilot hydraulic oils.

The left joystick controls the slewing mechanism and the auxiliary winch;

The right joystick controls the derricking mechanism and the main winch;

The pedals control telescoping and left/right crane travelling.

Multiple movements can be compounded.

Air conditioning

Adopts a standard heating and cooling air conditioning system, and optimizes air duct and air outlet.

1.14. Crane undercarriage

Traveling power

Both left and right crawler carriers are fitted with an independent hydraulic driving system. Each hydraulic driving system has a hydraulic motor, which can drive the drive sprocket via a planet reducer.

The operator can use the joystick or travel gear pedals to control traveling movements, such as traveling straight ahead / backwards, turning with a crawler, differential steering and turning on spot.

Traveling brake

The travel gear can be braked via the spring on the traveling motor, which is controlled by a balance valve.

• Crawler carrier extending & retracting mechanism

Crawler carriers are extended and retracted via two hydraulic cylinders.

- Crawler carrier extended:

Distance between track centers: 5400mm

- Crawler carrier retracted:

Distance between track centers: 2700mm

Track roller

A maintenance-free, sealed structure

Track pad

A high-strength alloy cast steel track pad, its width: 850 mm.

Traveling speed

The highest traveling speed is 1.5 km/h.

1.15. Safety devices

Many safety devices, including mechanical, electronic or hydraulic ones, are fitted on the crane to ensure safe operations.

Load moment limiter

The load moment limiter can automatically detect a boom angle and lifting load, and provide feedback of these data to the operator according to actual lifting situation.

When the normal operating range of the crane is exceeded, the load moment limiter will send out an alarm and limit current movement.

The LCD screen can show the following data: moment ratio, main boom angle, main boom length, working radius, actual load, and permissible lifting load, etc.

Hoisting limit switch

A hoisting height limit switch with a limit switch weight is installed on the top of the main boom section. It is used to prevent the hook from being lifted to the upper limit position. When the hook reaches the upper limit position, the limit switch is triggered and sends a signal to the crane's electrical system, which will cut off further lifting of the hook and trigger visual and acoustic alarm in the cab through a buzzer and an alarm indicator.

Lowering limit switch

When there are only three wraps of wire rope left on the drum, the lowering limit switch will be triggered, the buzzer will ring, the warning light on the screen will flash and the crane movement "reel off winch" will be cut off.

Slewing locking device

It adopts both electrical and mechanical locking, generally used to fix the relative position between the superstructure and undercarriage during transportation, so as to avoid accidental misoperation.

Safety catch

A device to protect the lifted load from falling off from the hook

Anemometer

An electronic wind speed sensor to indicate actual wind speed at the boom/jib head to the crane operator

Rear-view mirror

Located in the left front of the cab, and near the handrail in the right hood

Overflow valves in hydraulic system

The overflow valve fitted in the hydraulic system can restrain pressure in oil circuits from rising irregularly, thus protecting such hydraulic elements as the hydraulic oil pump and hydraulic motor against damage and the hydraulic system from being overloaded.

Emergency stop button

It allows the engine to be shut down and all movements to be stopped in an emergency situation.

Tricolor warning light

The warning light, by illuminating in red, yellow or green color, can indicate different loading status.

- Green color the load ratio is less than 90%
- Yellow color the load ratio is between 90% and 100%
- Red color the load ratio has exceeded 100% and the crane is overloaded.

Slewing alarm

An acoustic alarm will be sent out during slewing movements.

Traveling alarm

An acoustic alarm will be sent out during traveling movements.

Video monitoring system (optional)

A camera and a visual monitoring system are optional. They respectively monitor working conditions of the crane's hoisting winches and the blind spots behind the crane.

2. Work conditions and rated capacity charts

2. 1. Working range

2.1.1 Lifts with the boom only

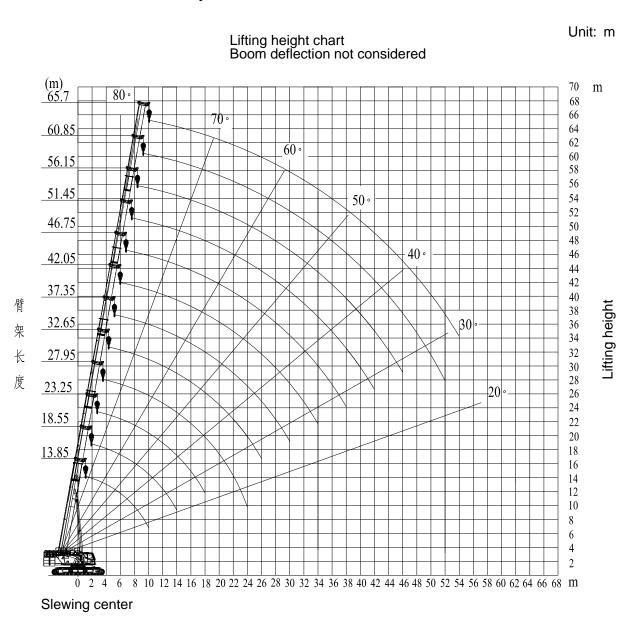


Figure 2-1 Lifting height chart

2.1.2 Lifts with boom and jib

2.1.2.1 Boom + 10.4m jib

Unit: m

Lifting height chart (60.85m boom + 10.4 m jib) Boom deflection not considered

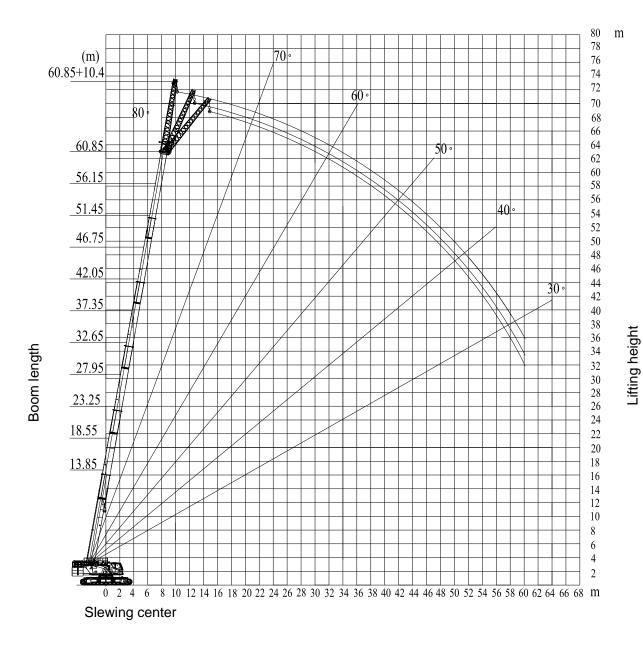


Figure 2-2 Lifting height chart

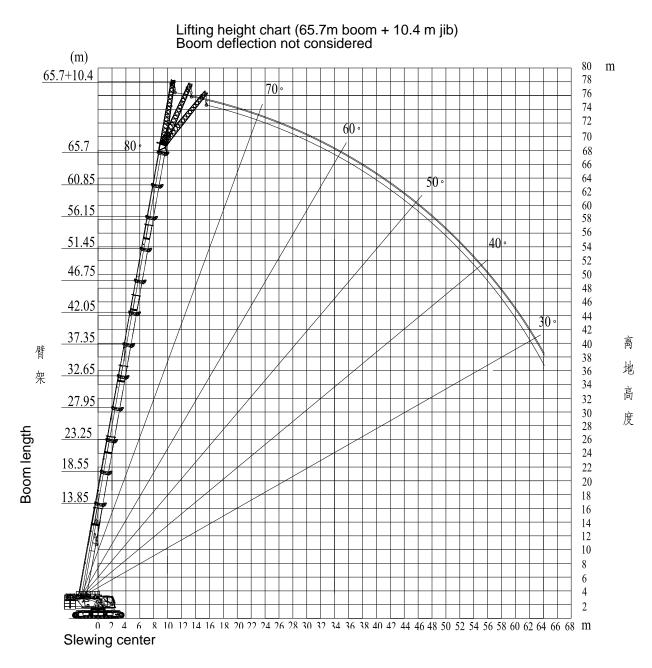
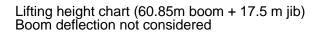


Figure 2-3 Lifting height chart

Lifting height

2.1.2.2 Boom + 17.5m jib



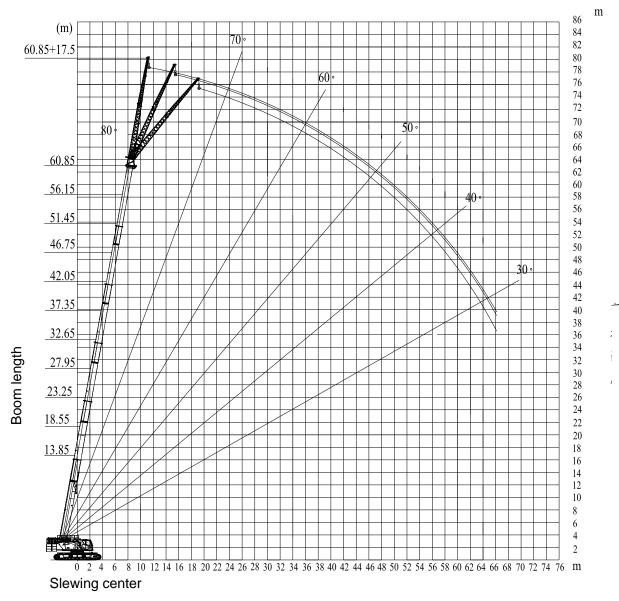
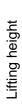
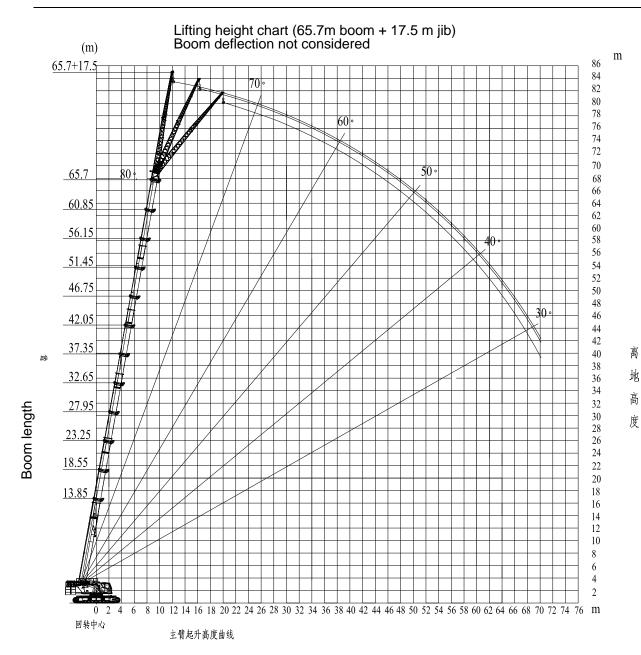


Figure 2-4 Lifting height chart





Slewing center

t chart

Lifting height

2.1.2.3 Boom + 4.9m tip boom

Lifting height chart (boom + tip boom) Boom deflection not considered

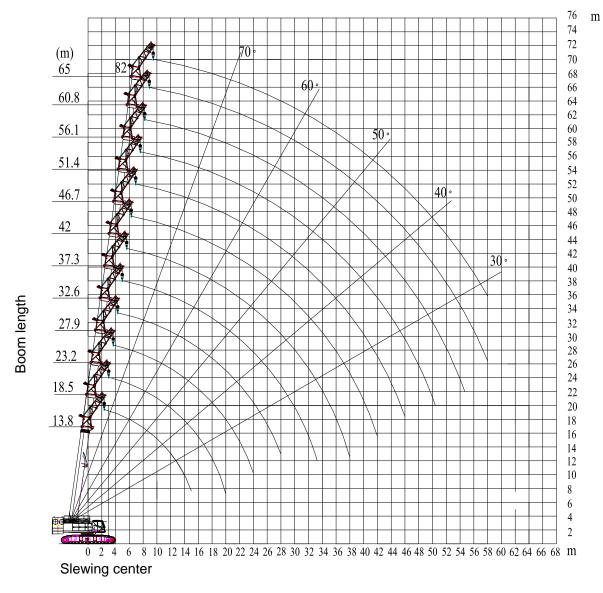


Figure2-6 Lifting height chart

2. 2. Rated lifting capacity with boom

Table 2-1 Rated capacity chart with boom

	360-degree	working ran	ge, 34t counte	erweight, 11t b	alance counte	rweight, crav	wler carriers f	ully extended	Offic. t
Working	Working Boom length (m)							Working	
radius	13.85 ★	18.55★	18.55	18.55	18.55	23.25★	23.25	23.25	radius
2.5									2.5
3	120	92	40	90	85				3
3.5	105	89	38	86	78	85	27	83	3.5
4	95	87	37	83	73	85	26	83	4
4.5	90	83	35	77	68	80	25	78	4.5
5	85	78	33	72	64	78	23.5	75	5
5.5	80	75	32	68	60	75	22	72	5.5
6	75	72	30	64	57	72	21	68	6
6.5	69	69	29	60	54	70	20	65	6.5
7	64	64	28	58	51	63	19	62	7
8	51	51	26	52	47	50	18	51	8
9	43	42	24.5	43	43	41	16.5	42	9
10	36	35	23	36	36	35	15	35.7	10
11	30	30	21.5	30	31	30	14.5	30.5	11
12		26.5	20.5	27	27	26	13.5	26.7	12
13		23.5	19.5	23.5	24	22.5	12.5	23.5	13
14		20.8	18.5	21	21	20	12	21	14
15		18	18	18.5	19	17.6	11.3	18.5	15
16			17.5	16.5	17	16	10.7	16.8	16
18						13	9.8	13.6	18
20							9	11.3	20
22									22
24									24
26									26
28									28
30									30
32									32
34									34
36									36
38									38
40									40
42									42
44									44
46									46
48									48
50									50
52									52
54									54
56									56
Reeving	12	12	6	12	12	11	4	11	Reeving
Main hook	120T	120T	75T	120T	120T	120T	75T	120T	Main hook
Tele I	1	1	1	1	1	2	1	1	I Tele
SCO	1	2	1	1	1	2	1	2	II sco
ping III	1	1	1	2	1	1	1	2	III ping
Telescoping mode	1	1	1	1	2	1	1	1	I Telescoping mode
ode V	1	1	2	1	1	1	3	1	V ode

Table 2-1 Rated capacity chart with boom

	360 dograd	working ran	an 24t count	erweight, 11t b	alanco counto	rwoight cra	wlor carriors f	ully extended	Unit: t
	Joo-degree	working ran	ige, 54t counte			rweight, cra	wiei camers i	ully exterioed	M/a alsia a
Working		1	1	1	ength (m)	_			Working
radius	23.25	23.25	27.95★	27.95	27.95	27.95	27.95	32.65★	radius
2.5									2.5
3									3
3.5	42	64							3.5
4	40	60	75	28.5	68	43.5	32		4
4.5	38	56	72	27	64.5	41.5	30		4.5
5	37	53	70	26	61	40	28.5	65	5
5.5	36	50	68	25	58	39	27	62	5.5
6	34	47	65	24	55	37.5	25.5	58	6
6.5	33	45	60	23	53	36	24.2	56	6.5
7	32	43	58	22	50	35	23	54	7
8	30	39	50	20	46	33	21.2	50	8
9	28	36	42	18.7	42	31	19.5	42	9
10	26	33	35	17.5	36	29	18	36	10
11	25	30.5	30	16.5	31.5	27	17	31	11
12	23.5	27	26	15.5	27.5	25	16	27	12
13	22.5	24.5	23	14.5	24	23.5	15	23.6	13
14	21.7	22	20	13.8	21.5	22	14	21.2	14
15	20	19.5	18	13.2	19.2	20.5	13.2	18.6	15
16	18	17.5	16.2	12.5	17.5	18.5	12.5	17	16
18	15	14.6	13.2	11.5	14.5	15.5	11.3	14	18
20	13	12.3	11	10.6	12.2	13	10.3	11.7	20
22			9.2	9.7	10.3	11.2	9.5	9.8	22
24			7.6	9	8.8	9.7	8.8	8.4	24
26								7.2	26
28								6	28
30								5.2	30
32									32
34									34
36									36
38									38
40									40
42									42
44									44
46									46
48									48
50									50
52									52
54									54
56									56
Reeving	6	8	9	4	9	6	4	8	Reeving
Main hook	75T	75T	75T	75T	75T	75T	75T	75T	Main hook
Telescoping mode	1	1	2	1	1	1	1	2	I Telescoping mode
SC II	1	1	2	1	2	1	1	2	II SCO
ping	1	2	2	1	2	2	1	2	III ping
ğ IV	2	2	1	2	2	2	3	2	IV
ode V	2	1	1	3	1	2	2	1	V de

(Continued) Table 2-1 Rated capacity chart with boom

	360-dograd	working ron	nge 3/t count	anweight 11th	alance counte	rweight cro	wler carriers fo	ully extended	Offit. t
	360-degree	e working rar	ige, 34t counte	-		rweight, cra	wier carriers it	ully extended	•
Working					ength (m)				Working
radius	32.65	32.65	32.65	32.65	37.35★	37.35	37.35	37.35	radius
2.5									2.5
3									3
3.5									3.5
4									4
4.5	26	45	30	30					4.5
5	25	43.5	28	28					5
5.5	23.5	42	26.5	26.8			24	29.5	5.5
6	22.5	41	25.5	25.5	41	23	23	28	6
6.5	21.5	40	24	24	41	22	21.6	27	6.5
7	20.5	38.5	23	23	40	21	20.6	26	7
8	18.5	36	21	21	39	19	19	23.5	8
9	17	34.5	19.2	19.5	37	17.5	17.3	22	9
10	16	32.5	17.8	17.8	36	16.2	16	20.3	10
11	15	31	16.5	16.5	32	15	15	19	11
12	14	28	15.5	15.5	27.5	14	14	18	12
13	13	25	14.5	14.5	24.5	13.2	13	17	13
14	12.3	22.5	13.6	13.7	21.8	12.5	12.2	16	14
15	11.5	20	12.8	13	19.7	11.8	11.5	15	15
16	11	18.2	12	12.3	17.8	11	11	14	16
18	9.8	15.2	10.8	11	14.7	10	9.7	12.8	18
20	9	13	9.8	10	12.5	9	8.8	11.5	20
22	8.2	11	9	9	10.5	8.2	8	10.5	22
24	7.5	9.5	8.2	8.3	9.1	7.7	7.3	9.6	24
26	7	8.4	7.5	7.8	7.8	7	6.7	8.4	26
28	6.5	7.3	7	7.1	6.8	6.5	6.2	7.4	28
30	6	6.4	6.5	6.7	5.9	6	5.7	6.5	30
32						5.6	5.3	5.7	32
34						5.3	4.9	5	34
36									36
38									38
40									40
42									42
44									44
46									46
48									48
50									50
52									52
54									54
56									56
Reeving	4	6	4	4	6	4	4	4	Reeving
Main hook	75T	75T	75T	75T	75T	25T	25T	75T	Main hoo
	1	1	1	1	2	1	1	1	
Telescoping mode	1	2	1	1	2	1	1	2	I II III IV V
opir III	1	2	3	2	2	2	3	3	III Sopir
ng IV	3	2	2	3	2	3	3	2	IV
mod V					2				V
e V	3	2	2	2	2	3	2	2	v de

(Continued) Table 2-1 Rated capacity chart with boom

	360-degree	working ran	ge, 34t counte	erweight, 11t b	alance counte	rweight, cra	wler carriers fo	ully extended	Offic. t
Working		Boom length (m)							Working
radius	37.35	42.05★	42.05	42.05	42.05	42.05	46.75★	46.75	radius
2.5									2.5
3									3
3.5									3.5
4									4
4.5									4.5
5									5
5.5	35.5								5.5
6	34								6
6.5	32		20		24	30			6.5
7	30.5	36	19	33	22.8	28			7
8	28	35	17.5	30.5	21	26		19	8
9	26	32	16.2	28	19.5	24	28	17.7	9
10	24	30	15	26.3	18	22	26	16.5	10
11	22.5	28	14	25	16.8	20.5	25	15.5	11
12	21	26	13	23	15.8	19	23	14.5	12
13	19.5	23.6	12.2	22	14.8	18	22	13.5	13
14	18.5	21.5	11.3	20.5	13.8	17	21	12.9	14
15	17.5	19	10.7	19.5	13	16	19	12.1	15
16	16.5	17	10	17.5	12.4	15	17.5	11.5	16
18	14.8	14	9	14.5	11.2	13.5	14.5	10.2	18
20	12.8	12	8.1	12.4	10.2	12.1	12	9.3	20
22	11	10.2	7.5	10.5	9.3	11	10.2	8.5	22
24	9.5	8.7	6.8	9	8.5	9.5	8.7	7.8	24
26	8.2	7.5	6.2	7.8	7.8	8.4	7.5	7.3	26
28	7.2	6.5	5.7	6.7	7.2	7.3	6.4	6.7	28
30	6.2	5.5	5.3	5.8	6.7	6.5	5.5	6.2	30
32	5.5	4.7	4.9	5	6	5.7	4.7	5.7	32
34	4.8	4	4.6	4.4	5.4	5	4	5.4	34
36		3.5	4.3	3.8	4.8	4.4	3.5	5	36
38		2.9	4	3.2	4.2	3.8	2.9	4.6	38
40							2.4	4.1	40
42							2	3.7	42
44							1.6	3.3	44
46									46
48									48
50									50
52									52
54									54
56									56
Reeving	6	5	4	4	4	4	4	3	Reeving
Main hook	75T	75T	25T	75T	25T	75T	75T	25T	Main hool
Telescoping mode	1	3	1	2	1	1	3	1	I Telescoping mode
S II	3	2	1	3	2	3	3	2	II ŠCO
pi. III	2	2	3	2	3	3	2	3	III pin
m IV	2	2	3	2	3	2	2	3	IN B
g V	2	2	3	2	2	2	2	3	V

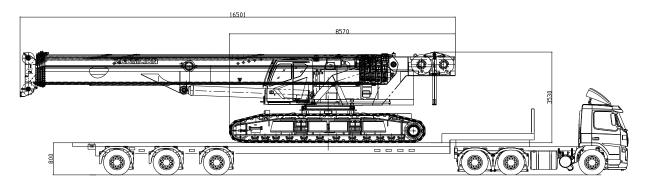
(Continued) Table 2-1 Rated capacity chart with boom

	360-degre	e working ra	inge, 34t coun	terweight, 1	1t balance c	ounterweigh	nt, crawler	carriers fully	extended	Offic. t
Working	Boom length (m)								Working	
radius	46.75	46.75	51.45★	51.45	51.45	56.15	56.15	60.85★	65.7★	radius
2.5										2.5
3										3
3.5										3.5
4										4
4.5										4.5
5										5
5.5										5.5
6										6
6.5										6.5
7										7
8	27	22.7								8
9	25.5	21		19	22.2					9
10	24	20	23.5	18	21					10
11	22.5	18.5	23	17	20	19	17.5			11
12	21	17.5	21	16	18.8	18	16.5			12
13	19.8	16.5	20	15	17.8	17	15.8	16		13
14	18.6	15.6	19	14	16.8	16	15	15.5	13.5	14
15	17.5	14.6	18	13.5	16	15.5	14.2	14.8	13	15
16	16.5	13.8	17	12.8	15.2	15	13.5	14.2	12.5	16
18	14.8	12.6	14	11.5	14	13.5	12.3	13	12	18
20	12.5	11.5	12	10.5	12.8	11.5	11.4	11.9	11	20
22	10.7	10.5	10.2	9.7	10.9	10	10.4	10.4	10	22
24	9.2	9.5	8.7	8.9	9.5	9	9.7	8.8	9	24
26	8	8.7	7.5	8.2	8.2	7.9	8.5	7.8	7.8	26
28	6.9	7.5	6.5	7.6	7.2	6.8	7.4	6.8	6.8	28
30	6	6.7	5.6	7	6.3	5.9	6.5	6.2	6	30
32	5.2	5.9	4.9	6.3	5.5	5.2	5.8	5.5	5.3	32
34	4.5	5.2	4.2	5.6	4.8	4.5	5.2	4.8	4.6	34
36	4	4.6	3.6	5	4.3	3.9	4.5	4.1	4	36
38	3.4	4.1	3.1	4.5	3.7	3.4	4	3.7	3.6	38
40	2.9	3.6	2.6	4	3.3	2.8	3.5	3.2	3.2	40
42	2.5	3.2	2.2	3.6	2.8	2.5	3.1	2.8	2.75	42
44	2.3	2.8	1.8	3.2	2.4	2.1	2.7	2.4	2.4	44
46				2.8	2	1.7	2.4	2.1	2	46
48				2.5	1.7	1.4	2	1.8	1.7	48
50						1.1	1.8	1.5	1.45	50
52							1.5	1.2	1.2	52
54									0.95	54
56									3.55	56
Reeving	4	3	3	3	3	3	3	2	2	Reeving
Main hook	75T	25T	25T	25T	25T	25T	25T	25T	25T	Main hoo
	2	1	3	1	2	3	2	3	4	
esc	3	3	3	3	3	3	3	3	4	I II III IV V
ğ <u>II</u>	3	3	3	3	3	3	3	3	4	ш <u>ө</u>
Telescoping mode										III oing
a IV	2	3	2	3	3	3	3	3	4	IV m
V	2	2	2	3	2	2	3	3	4	V de

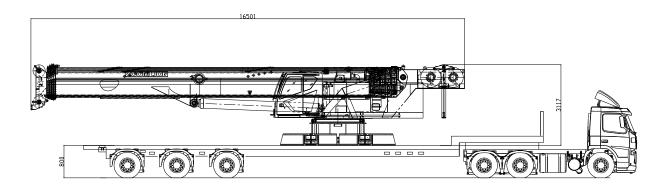
3. Transport dimensions

Based on a common dismantling principle, this crane can be dismantled into several large parts for transportation.

Transportation plan 1: remove the counterweight and balance weight from the crane body, and transport the crane body (61 t) by one trailer; transport the counterweight and balance counterweight (45 t) by another trailer.

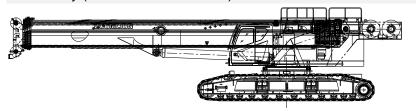


Transportation plan 2: remove the counterweight and balance weight, left and right crawler carriers from the crane body, and transport the crane body (42 t) by one trailer; transport the counterweight and balance counterweight by a second trailer; transport the left and right crawler carriers by a third trailer.



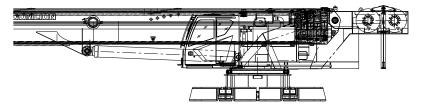
Main components and their dimensions and weight

Crane body (with the crawler carrier)



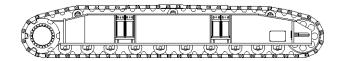
Length mm	16500
Width mm	3580
Height mm	3530
Weight kg	61000

Crane body (without the crawler carrier)



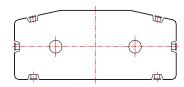
16500
2990
3117
43000

Crawler carrier assembly X2



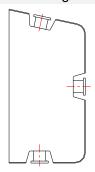
Length mm	7420
Width mm	850
Height mm	1150
Weight kg	9500

Counterweight plate X3



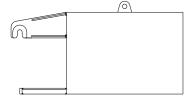
Length mm	3800
Width mm	1600
Height mm	410
Weight kg	9000

Left and right counterweight plates X2



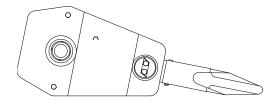
Length mm	1500
Width mm	800
Height mm	1250
Weight kg	3500

Fixed balancing counterweight X2



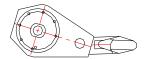
Length mm	1953
Width mm	1300
Height mm	752
Weight kg	5500

75 t hook



Length mm	1658
Width mm	650
Height mm	567
Weight kg	768

9 t hook



Length mm	900
Width mm	370
Height mm	370
Weight kg	320

Note:

- 1. The components above are only schematic, and they are not drawn according to a fixed scale. The length dimension is overall dimension.
- 2. The weight listed in above table does not include the weight of package. The actual weight of a component may be different from the weight listed in above table due to manufacturing error.
- 3. The components above may be improved, which will result in changes in dimensions and weight. Therefore, the actual weight and dimension should be subject to factory products.
- 4. There are 4 configurations of the main hook: 120 t, 75 t, 25 t, and 9 t. Among them, the 75 t straight shank twin hooks and 9 t straight shank single hook are standard configuration, while the 120 t straight twin hooks and 25 t straight shank single hook are optional.